

Quantum Random, Self-Modifiable Computation

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Standard Model of Computation

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An ex-machine can make a computational mistake on a first instance of a problem and subsequently repair its program before executing on a second instance of the same problem.

Preliminaries

From $\{a\}^*$, define the set of languages $\mathfrak{L} = \bigcup_{L \subset \{a\}^*} \{L\}$.

For $f : \mathbb{N} \rightarrow \{0, 1\}$, define language $L_f = \{a^n : f(n) = 1\}$.

$$\mathfrak{L} = \bigcup_{f \in \{0,1\}^{\mathbb{N}}} \{L_f\}$$

Let μ be the Lebesgue measure on $\{0, 1\}^{\mathbb{N}}$. $\mu(\{0, 1\}^{\mathbb{N}}) = 1$.

μ induces Lebesgue measure ν on \mathfrak{L} via $f \leftrightarrow L_f$. $\nu(\mathfrak{L}) = 1$.

Set Alphabet $A = \{\#, 0, 1, N, Y, a\}$. $\#$ is the blank symbol.

Set States $Q = \{0, h, n, y, t, v, w, x, 8\}$ with halting state h

$\Omega(x)$ Specification: 15 Initial Instructions

$(0, \#, 8, \#, 1)$

$(8, \#, x, \#, 0)$

$(y, \#, h, Y, 0)$

$(n, \#, h, N, 0)$

$(x, \#, x, 0)$

$(x, a, t, 0)$

$(x, 0, v, \#, 0, (|Q| - 1, \#, n, \#, 1))$

$(x, 1, w, \#, 0, (|Q| - 1, \#, y, \#, 1))$

$(t, 0, w, a, 0, (|Q| - 1, \#, n, \#, 1))$

$(t, 1, w, a, 0, (|Q| - 1, \#, y, \#, 1))$

$(v, \#, n, \#, 1, (|Q| - 1, a, |Q|, a, 1))$

$(w, \#, y, \#, 1, (|Q| - 1, a, |Q|, a, 1))$

$(w, a, |Q|, a, 1, (|Q| - 1, a, |Q|, a, 1))$

$(|Q| - 1, a, x, a, 0)$

$(|Q| - 1, \#, x, \#, 0)$

Main Results

$\Omega(x)$ computes Turing uncomputable languages in \mathfrak{L} with probability (Lebesgue measure) 1.

After a finite number of computational steps, $\Omega(x)$ uses a finite amount of computing resources.

Consider an enumeration $\mathcal{E}_a(i) = (\mathfrak{M}_i, T_i)$ of all Turing machines \mathfrak{M}_i and initial tapes T_i , each containing a finite number of non-blank symbols.

There exists an evolutionary path $\Omega(x) \rightarrow \Omega_1 \rightarrow \Omega_2 \rightarrow \dots \rightarrow \Omega_m$, so at the m th stage Ω_m correctly determines for $0 \leq i \leq m$ whether \mathfrak{M}_i 's execution on tape T_i halts.

Key Observations

$p = \frac{1}{2}$. Our random instructions use no hidden tricks, e.g. p is Turing incomputable.¹

In practice, $\Omega(x)$ will not find this evolutionary halting path, even though it is possible. (Impossible for a Turing machine.)

$\Omega(x)$'s dynamical behavior circumvents the contradiction in an information-theoretic proof of Turing's halting problem.²

The circumvention occurs because $\Omega(x)$'s meta instructions increase the number of states and instructions in $\Omega(x)$.

¹K. de Leeuw, E.F. Moore, C. Shannon, N. Shapiro. Computability by Probabilistic Machines. Princeton University Press. 1956.

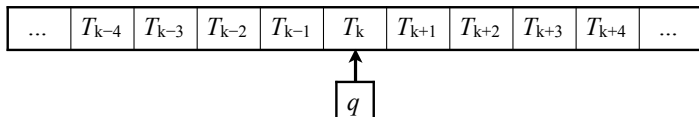
²C. Calude. Information and Randomness. Springer. 1994. pp. 184-185

Standard Instructions \mathcal{S} : (q, T_k, r, b, y)

Standard Instructions are Turing machine instructions.

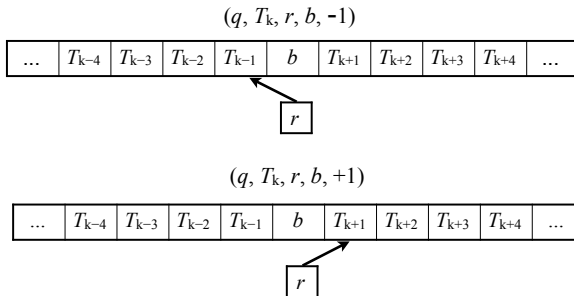
$Q = \{0, 1, \dots, n-1\} \subset \mathbb{N}$ is the set of states.

Alphabet $A = \{0, 1, \#\} \cup \{a_1, \dots, a_m\}$. $\#$ is the blank symbol.



Standard Instructions \mathcal{S}

Reading T_k on the tape in state q , write b on tape and move to state r . Move tape head $y \in \{-1, 0, 1\}$.



Random Instructions \mathcal{R} : (q, a, r, y)

When scanning alphabet symbol a and lying in state q , random instruction (q, a, r, y) executes as follows.

Measure a quantum event that returns a random $b \in \{0, 1\}$.

On the tape, replace alphabet symbol a with random bit b .
(Alphabet A always contains symbols $\{0, 1\}$.)

The ex-machine state moves to state r .

The ex-machine moves its tape head left if $y = -1$, right if $y = +1$, or does not move if $y = 0$.

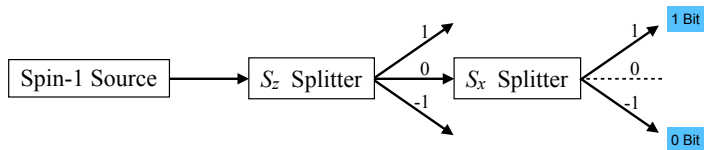
Quantum Random Axioms

Unbiased Trials: Consider bit sequence $(x_1 x_2 x_3 \dots)$ in the infinite product space $\{0, 1\}^{\mathbb{N}}$. A single outcome x_i generated by quantum randomness is unbiased. The probabilities satisfy $P(x_i = 1) = P(x_i = 0) = \frac{1}{2}$.

Stochastic Independence: History has no effect on the next quantum random measurement. Each outcome x_i is independent of the history. Expressed as conditional probabilities, $P(x_i = a \mid x_1 = b_1, \dots, x_{i-1} = b_{i-1}) = \frac{1}{2}$ for $a = 0, a = 1$ and for each $(b_1, b_2, \dots, b_{i-1}) \in \{0, 1\}^{i-1}$.

A Theory for a Quantum Random Number Generator

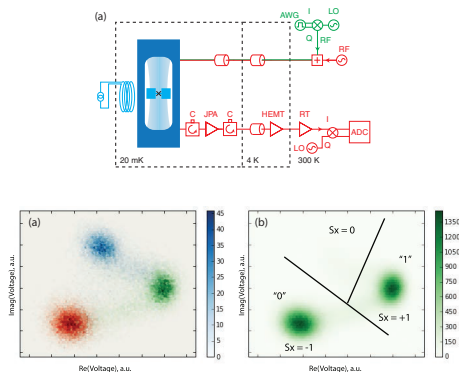
Protocol for a QRNG Based on Value Indefiniteness³



³Abbott, Calude, Conder, Svozil. Strong Kochen-Specker theorem and incomputability of quantum randomness. Physical Review A 86, 062109, 2012.

A Physical Realization of a QRNG

Measurement Setup and S_x Data ⁴



⁴Kulikov et al. Realization of a QRNG certified with the Kochen-Specker Theorem. 2017. arXiv:1709.03687v1

Meta Instructions \mathcal{M}

Meta instructions can add new states.

Meta instructions can add new instructions

Meta instructions can replace instructions.

Meta instructions \mathcal{M} are a subset of $\{(q, a, r, \alpha, y, J) : q \in Q$
and $r \in Q \cup \{|Q|\}$ and $a, \alpha \in A$ and instruction
 $J \in \mathcal{S} \cup \mathcal{R}\}$.

J is a standard or random instruction

Execution of Meta Instruction (q, a, r, α, y, J)

$$\mathcal{I} = \mathcal{S} \cup \mathcal{R} \cup \mathcal{M}.$$

Quintuple (q, a, r, α, y) executes as a standard instruction with one caveat:

State q may be expressed as $|Q| - c_1$ and state r may be expressed as $|Q|$ or $|Q| - c_2$, where $0 < c_1, c_2 \leq |Q|$. When (q, a, r, α, y) is executed, if q is expressed as $|Q| - c_1$, the value of q is instantiated to the current value of $|Q|$ minus c_1 .

If state r is expressed as $|Q|$ or $|Q| - c_2$, the value of r instantiates to the current value of $|Q|$ or $|Q| - c_2$, respectively.

Execution of Meta Instruction (q, a, r, α, y, J)

Unique state, scanning condition: for any two distinct instructions chosen from \mathcal{I} at least one of the first two coordinates must differ.

Next, instruction J modifies \mathcal{I} , where instruction J has one of the two forms: $J = (q, a, r, \alpha, y)$ or $J = (q, a, r, y)$.

For both forms, if $\mathcal{I} \cup \{J\}$ still satisfies the unique state, scanning symbol condition, then \mathcal{I} is updated to $\mathcal{I} \cup \{J\}$.

Otherwise, there is an instruction I in \mathcal{I} whose first two coordinates q, a are equal to instruction J 's first two coordinates. In this case, instruction J replaces instruction I in \mathcal{I} . That is, \mathcal{I} is updated to $\mathcal{I} \cup \{J\} - \{I\}$

Example that Executes a Meta Instruction

Consider meta instruction $(q, a_1, |Q| - 1, \alpha_1, y_1, J)$, where $J = (|Q| - 1, a_2, |Q|, \alpha_2, y_2)$.

After standard instruction $(q, a_1, |Q| - 1, \alpha_1, y_1)$ executes, this meta instruction adds a new state $|Q|$ to the states Q and adds instruction J , instantiated with the current value of $|Q|$.

Set states $Q = \{0, 1, 2, 3, 4, 5, 6, 7\}$. Alphabet $A = \{\#, 0, 1\}$.

An initial configuration is shown below.

State	Tape
5	##11 01##

Example that Executes a Meta Instruction

Meta instruction $(5, 0, |Q| - 1, 1, 0, J)$ executes with values $q = 5$, $a_1 = 0$, $\alpha_1 = 1$, $y_1 = 0$, $a_2 = 1$, $\alpha_2 = \#$, and $y_2 = -1$.

Instruction $J = (|Q| - 1, 1, |Q|, \#, -1)$

Since $|Q| = 8$, instruction $(5, 0, 7, 1, 0)$ executes.

$J = (7, 1, 8, \#, -1)$ is added as a new standard instruction.

The instantiation of $|Q| = 8$ in J adds state 8. The states are updated to $Q = \{0, 1, 2, 3, 4, 5, 6, 7, 8\}$.

The new ex-machine configuration is shown below.

State	Tape
7	##11 11##

Example that Executes a Meta Instruction

State	Tape
7	##11 11##

Now, the ex-machine is scanning a 1 and lying in state 7, so the standard instruction $J = (7, 1, 8, \#, -1)$ executes.

Note J was just added to the instructions.

After J executes, the new configuration is shown below.

State	Tape
8	##1 1#1##

Simple Meta Instructions

A simple meta instruction has syntax, where $0 < c_1, c_2 \leq |Q|$:

$$(q, a, |Q| - c_2, \alpha, y) \quad \text{or} \quad (q, a, |Q|, \alpha, y)$$

$$(|Q| - c_1, a, r, \alpha, y)$$

$$(|Q| - c_1, a, |Q| - c_2, \alpha, y) \quad \text{or} \quad (|Q| - c_1, a, |Q|, \alpha, y).$$

Expressions $|Q| - c_1$, $|Q| - c_2$ and $|Q|$ are instantiated to a state based on the current value of $|Q|$ when the meta instruction executes.

$\Omega(x)$ self-reflects with the symbols $|Q| - 1$ and $|Q|$.

Finite Initial Conditions

A *finitely bounded tape* means the tape has a finite number of non-blank symbols.

An ex-machine has *finite initial conditions* if the following 4 conditions are satisfied before the ex-machine starts executing.

1. The number of states $|Q|$ is finite.
2. The number of alphabet symbols $|A|$ is finite.
3. The number of machine instructions $|I|$ is finite.
4. The tape is finitely bounded.

Evolving an Ex-machine

T_0, T_1, \dots, T_{i-1} are finitely bounded tapes. Ex-machine \mathfrak{X}_0 has finite initial conditions.

\mathfrak{X}_0 starts executing with tape T_0 and evolves to ex-machine \mathfrak{X}_1 with tape S_1 .

Next, \mathfrak{X}_1 starts executing with tape T_1 and evolves to \mathfrak{X}_2 with tape S_2 . This means that when ex-machine \mathfrak{X}_1 starts executing on tape T_1 , its instructions are preserved after the halt with tape S_1 .

The ex-machine evolution continues until \mathfrak{X}_{i-1} starts executing with tape T_{i-1} and evolves to ex-machine \mathfrak{X}_i with tape S_i .

Evolutionary Path, Ancestors and Descendants

One says that ex-machine \mathfrak{X}_0 with finitely bounded tapes $T_0, T_1, T_2 \dots T_{i-1}$ evolves to ex-machine \mathfrak{X}_i after i halts.

When ex-machine \mathfrak{X}_0 evolves to \mathfrak{X}_1 and subsequently \mathfrak{X}_1 evolves to \mathfrak{X}_2 and so on up to ex-machine \mathfrak{X}_n , then ex-machine \mathfrak{X}_i is called an *ancestor* of ex-machine \mathfrak{X}_j whenever $0 \leq i < j \leq n$.

Similarly, ex-machine \mathfrak{X}_j is called a *descendant* of ex-machine \mathfrak{X}_i whenever $0 \leq i < j \leq n$.

The sequence of ex-machines $\mathfrak{X}_0 \rightarrow \mathfrak{X}_1 \rightarrow \dots \rightarrow \mathfrak{X}_n \dots$ is called an *evolutionary path*.

Languages that $\Omega(x)$ Evolves to Compute

Recall that $\mathfrak{L} = \bigcup_{L \subset \{a\}^*} \{L\}$. Alphabet $A = \{\#, 0, 1, N, Y, a\}$. The initial states are $Q = \{0, h, n, y, t, v, w, x, 8\}$ with halting state h

Let \mathfrak{X} be an ex-machine that is a descendant of $\Omega(x)$. The language L in \mathfrak{L} that \mathfrak{X} computes is defined as follows.

A valid initial tape has the form $\# \# a^n \#$. The valid initial tape $\# \# \#$ represents the empty string.

After machine \mathfrak{X} starts executing with initial tape $\# \# a^n \#$, string a^n is in \mathfrak{X} 's language if \mathfrak{X} halts with tape $\# a^n \# Y \#$.

a^n is not in \mathfrak{X} 's language if \mathfrak{X} halts with tape $\# a^n \# N \#$.

$\Omega(x)$ Specification

$(0, \#, 8, \#, 1)$

$(8, \#, x, \#, 0)$

$(y, \#, h, Y, 0)$

$(n, \#, h, N, 0)$

$(x, \#, x, 0)$

$(x, a, t, 0)$

$(x, 0, v, \#, 0, (|Q| - 1, \#, n, \#, 1))$

$(x, 1, w, \#, 0, (|Q| - 1, \#, y, \#, 1))$

$(t, 0, w, a, 0, (|Q| - 1, \#, n, \#, 1))$

$(t, 1, w, a, 0, (|Q| - 1, \#, y, \#, 1))$

$(v, \#, n, \#, 1, (|Q| - 1, a, |Q|, a, 1))$

$(w, \#, y, \#, 1, (|Q| - 1, a, |Q|, a, 1))$

$(w, a, |Q|, a, 1, (|Q| - 1, a, |Q|, a, 1))$

$(|Q| - 1, a, x, a, 0)$

$(|Q| - 1, \#, x, \#, 0)$

$\Omega(x)$ Starts with Tape $\# \#aaaa\#\#$ and State 0

STATE	TAPE	INSTRUCTION EXECUTED	NEW INSTRUCTION
8	$\# \#aaaa\#\#\#$	$(0, \#, 8, \#, 1)$	
x	$\# \#aaaa\#\#\#$	$(Q - 1, a, x, a, 0)$	$(8, a, x, a, 0)$
t	$\# \#1aaa\#\#\#$	$(x, a, t, 1_{qr}, 0)$	
w	$\# \#aaaa\#\#\#$	$(t, 1, w, a, 0, (Q - 1, \#, y, \#, 1))$	$(8, \#, y, \#, 1)$
9	$\# \#a aaa\#\#\#$	$(w, a, Q , a, 1, (Q - 1, a, Q , a, 1))$	$(8, a, 9, a, 1)$
x	$\# \#a aaa\#\#\#$	$(Q - 1, a, x, a, 0)$	$(9, a, x, a, 0)$
t	$\# \#a 1aa\#\#\#$	$(x, a, t, 1_{qr}, 0)$	
w	$\# \#a aaa\#\#\#$	$(t, 1, w, a, 0, (Q - 1, \#, y, \#, 1))$	$(9, \#, y, \#, 1)$
10	$\# \#aa aa\#\#\#$	$(w, a, Q , a, 1, (Q - 1, a, Q , a, 1))$	$(9, a, 10, a, 1)$
x	$\# \#aa aa\#\#\#$	$(Q - 1, a, x, a, 0)$	$(10, a, x, a, 0)$
t	$\# \#aa 0a\#\#\#$	$(x, a, t, 0_{qr}, 0)$	
w	$\# \#aa aa\#\#\#$	$(t, 0, w, a, 0, (Q - 1, \#, n, \#, 1))$	$(10, \#, n, \#, 1)$
11	$\# \#aaa a\#\#\#$	$(w, a, Q , a, 1, (Q - 1, a, Q , a, 1))$	$(10, a, 11, a, 1)$
x	$\# \#aaa a\#\#\#$	$(Q - 1, a, x, a, 0)$	$(11, a, x, a, 0)$
t	$\# \#aaa 1\#\#\#$	$(x, a, t, 1_{qr}, 0)$	
w	$\# \#aaa a\#\#\#$	$(t, 1, w, a, 0, (Q - 1, \#, y, \#, 1))$	$(11, \#, y, \#, 1)$
12	$\# \#aaaa \#\#\#$	$(w, a, Q , a, 1, (Q - 1, a, Q , a, 1))$	$(11, a, 12, a, 1)$
x	$\# \#aaaa \#\#\#$	$(Q - 1, \#, x, \#, 0)$	$(12, \#, x, \#, 0)$
x	$\# \#aaaa 0\#\#$	$(x, \#, x, 0_{qr}, 0)$	
v	$\# \#aaaa \#\#\#$	$(x, 0, v, \#, 0, (Q - 1, \#, n, \#, 1))$	$(12, \#, n, \#, 1)$
n	$\# \#aaaa\# \#\#$	$(v, \#, n, \#, 1, (Q - 1, a, Q , a, 1))$	$(12, a, 13, a, 1)$
h	$\# \#aaaa\# N\#$	$(n, \#, h, N, 0)$	

$\Omega(x)$ Evolved to $\Omega(11010\ x)$

 $(0, \#, 8, \#, 1)$ $(y, \#, h, Y, 0)$ $(n, \#, h, N, 0)$ $(x, \#, x, 0)$ $(x, a, t, 0)$ $(x, 0, v, \#, 0, (|Q| - 1, \#, n, \#, 1))$ $(x, 1, w, \#, 0, (|Q| - 1, \#, y, \#, 1))$ $(t, 0, w, a, 0, (|Q| - 1, \#, n, \#, 1))$ $(t, 1, w, a, 0, (|Q| - 1, \#, y, \#, 1))$ $(v, \#, n, \#, 1, (|Q| - 1, a, |Q|, a, 1))$ $(w, \#, y, \#, 1, (|Q| - 1, a, |Q|, a, 1))$ $(w, a, |Q|, a, 1, (|Q| - 1, a, |Q|, a, 1))$ $(|Q| - 1, a, x, a, 0)$ $(|Q| - 1, \#, x, \#, 0)$ $(8, \#, y, \#, 1)$ $(8, a, 9, a, 1)$ $(9, \#, y, \#, 1)$ $(9, a, 10, a, 1)$ $(10, \#, n, \#, 1)$ $(10, a, 11, a, 1)$ $(11, \#, y, \#, 1)$ $(11, a, 12, a, 1)$ $(12, \#, n, \#, 1)$ $(12, a, 13, a, 1)$

$\Omega(x)$ Evolving to Compute Some L_f

Each infinite downward path in the infinite binary tree corresponds to a unique language L_f , where string a^n lies in L_f if and only if the $n + 1$ th branch of the downward path is a 1.

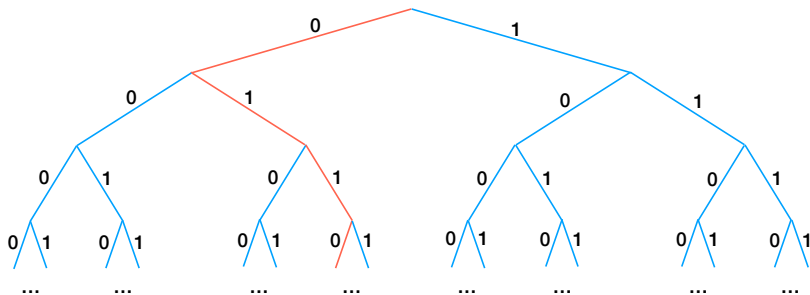


Figure: Infinite Binary Tree

$\Omega(x)$ Evolving to Compute Some L_f

An execution of $\Omega(x)$ on initial tape $\# \# a^n \#$ executes a random instruction $n + 1$ times, creating a finite downward path of length $n + 1$. After this execution, the descendant is $\Omega(f(0)f(1)\dots f(n) x)$, where $f(i)$ is the random bit measured in the $i + 1$ th execution of a random instruction.

LEMMA: Assume $i \leq n$. If $f(i) = 1$, then $\Omega(f(0)f(1)\dots f(n) x)$ on initial tape $\# \# a^i \#$ halts with tape $\# a^i \# \quad Y \#$. If $f(i) = 0$, then $\Omega(f(0)f(1)\dots f(n) x)$ halts with $\# a^i \# \quad N \#$.

THEOREM: For functions $f : \mathbb{N} \rightarrow \{0, 1\}$, the probability that language L_f is Turing uncomputable has measure 1 in (ν, \mathfrak{L}) .

COROLLARY: $\Omega(x)$ evolves to compute a Turing uncomputable language L_f with probability measure 1 in (ν, \mathfrak{L}) .

$\Omega(x)$ Evolving to Compute $L_{h_{\epsilon_a}}$

Universal Turing machine / enumeration theorem, there is a Turing computable enumeration $\mathcal{E} : \mathbb{N} \rightarrow \{ \text{all Turing machines } \mathcal{M} \} \times \{ \text{Each of } \mathcal{M}'\text{'s states as an initial state} \}$

This enumeration uses the blank-tape halting problem.

Set alphabet $\mathcal{A} = \{ \#, 0, 1, a, A, B, M, N, S, X, Y \}$.

Let $\mathcal{M}_{\mathcal{E}}$ be the Turing machine that computes $\mathcal{E}_a : \mathbb{N} \rightarrow \mathcal{A}^* \times \mathbb{N}$, where tape $\# \# a^n \#$ represents the natural number n in the domain of \mathcal{E}_a .

\mathbb{N} in the range of \mathcal{E}_a holds the initial state of machine $\mathcal{E}_a(n)$.

$\Omega(x)$ Evolving to Compute Halting Language $L_{h_{\mathcal{E}_a}}$

REMARK: For each $n \in \mathbb{N}$, with blank initial tape and initial state $\mathcal{E}_a(n)$ (2nd coordinate), then Turing machine $\mathcal{E}_a(n)$ (first coordinate) either halts or does not halt.

Define *halting function* $h_{\mathcal{E}_a} : \mathbb{N} \rightarrow \{0, 1\}$, where $h_{\mathcal{E}_a}(n) = 1$ if Turing machine $\mathcal{E}_a(n)$ halts with blank initial tape and initial state $\mathcal{E}_a(n)$. $h_{\mathcal{E}_a}(n) = 0$ if Turing machine $\mathcal{E}_a(n)$ does not halt.

Define *halting language* $L_{h_{\mathcal{E}_a}} = \{a^n : h_{\mathcal{E}_a}(n) = 1\}$.

THEOREM: The evolutionary path $\Omega(h_{\mathcal{E}_a}(0) \ x) \rightarrow \Omega(h_{\mathcal{E}_a}(0) \ h_{\mathcal{E}_a}(1) \ x) \rightarrow \dots \Omega(h_{\mathcal{E}_a}(0) \ h_{\mathcal{E}_a}(1) \ \dots \ h_{\mathcal{E}_a}(m) \ x) \dots$ computes halting language $L_{h_{\mathcal{E}_a}}$

Halting Complexity Questions

Can we find or define a measure of halting complexity to appropriately ask the next question?

(The Shannon complexity $|Q||A|$ is not adequate.)

Can this finite halting complexity of a Turing machine H be characterized as follows? There exists a threshold halting complexity $\theta(M)$ so that if M 's halting complexity is greater than $\theta(M)$, then H cannot determine M 's halting behavior.

(One approach is to assume an initially blank tape to assure that there is not complexity hidden in the different initial tapes.)

Self-Modification Questions

For a fixed Turing machine M , do there exist ex-machine self-modification procedures in some ex-machine X that start with a finite number of standard, random and meta instructions that can evolve to determine M 's halting behavior with probability measure 1?

Does there exist a sufficiently high halting complexity for M , where these self-modification procedures fail?